BOLT
OpenMP over Lightweight Threads

http://www.bolt-omp.org

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OpenMP

- Directive based programming model
- Commonly used for shared-memory programming in a node
- Many different implementations
  - Typically on top of Pthreads library
  - Intel, GCC, Clang, IBM, etc.

**Sequential code**
```c
for (i = 0; i < N; i++) {
    do_something();
}
```

**OpenMP code**
```c
#pragma omp parallel for
for (i = 0; i < N; i++) {
    do_something();
}
```
Nested Parallel Loop: Microbenchmark

```c
int in[1000][1000], out[1000][1000];

#pragma omp parallel for
for (i = 0; i < 1000; i++) {
    lib_compute(i);
}

lib_compute(int x)
{
    #pragma omp parallel for
    for (j = 0; j < 1000; j++)
        out[x][j] = compute(in[x][j]);
}
```

A thread for each CPU is created by default
Each thread executes a portion
Each thread creates more threads for the second loop
Each inner thread executes a portion

Contribution: Adrian Castello (Universitat Jaume I)
Nested Parallel Loop: Performance

Execution time for 36 threads in the outer loop

GCC OpenMP implementation does not reuse idle threads in nested parallel regions, all the teams of threads need to be created in each iteration.

Some overhead is added by creating ULTs instead of tasks.
BOLT: A Lightning-Fast OpenMP Implementation

• About BOLT
  – BOLT is a recursive acronym that stands for "BOLT is OpenMP over Lightweight Threads"
  – http://www.bolt-omp.org

• Objective
  – OpenMP framework that exploits lightweight threads and tasks

- Improved Nested Massive Parallelism
- Enhanced Fine-Grained Task Parallelism
- Better Interoperability with MPI and Other Internode Programming Models
Approach & Development

• Basic approach
  – Compiler simply generates runtime API calls, while the runtime creates ULTs/tasklets and manages them over a fixed set of computational resources
  – Use Argobots as the underlying threading and tasking mechanism
  – ABI compatibility with Intel OpenMP compilers, LLVM/Clang, and GCC (i.e., can be used with these compilers)

• Development
  – Runtime
    • Based on Intel OpenMP Runtime API
    • Generates Argobots work units from OpenMP pragmas
    • Can generate ULTs or tasklets depending on code characteristics
  – Compiler (planned)
    • LLVM/Clang
    • Passes characteristics of parallel region or task (e.g., existence of blocking calls) to the runtime
    • Extends pragmas with the option “nonblocking”
Argobots

Overview
• Separation of mechanisms and policies
• Massive parallelism
  – Exec. Streams guarantee progress
  – Work Units execute to completion
    • User-level threads (ULTs) vs. Tasklets
• Clearly defined memory semantics
  – Consistency domains
    • Provide Eventual Consistency
  – Software can manage consistency

Argobots Innovations
• Enabling technology, but not a policy maker
  – High-level languages/libraries such as OpenMP or Charm++ have more information about the user application (data locality, dependencies)
• Explicit model:
  – Enables dynamism, but always managed by high-level systems

* Current team members: Pavan Balaji, Sangmin Seo, Halim Amer (ANL), L. Kale, Nitin Bhat, Prateek Jindal (UIUC)
**BOLT Execution Model**

- OpenMP threads and tasks are translated into Argobots work units (i.e., ULTs and tasklets)
- Shared pools are utilized to handle nested parallelism
- A customized Argobots scheduler manages scheduling of work units across execution streams
OpenMP Pragma Translation

1. A set of $N$ threads is created at run time
   - If they have not been created yet
   - Commonly as many as the number of CPU cores
2. The number of iterations is divided between all the threads
3. A synchronization point is added after the for loop
   - Implicit barrier at the end of parallel for

```c
#pragma omp parallel for (1,2)
for (i = 0; i < N; i++) {
    do_something();
}
```
OpenMP Compiler & BOLT Runtime

#pragma omp parallel
Clang and Intel compiler

__kmpc_fork_call(...){
  __kmp_fork_call(...)
  __kmp_join_call(...)
}

Intel OpenMP Runtime API

BOLT runtime

• Create Execution Streams (if needed)
• Add a ULT or tasklet to each ES
• Launch the work

• Join work units created
parallel for

```c
#pragma omp parallel for
for (i = 0; i < N; i++) {
    do_something();
}
```

- Creates threads
- Divides all iterations among threads
- Synchronization point

Implementation using Argobots

One Execution Stream for each CPU core (or hardware thread)

Each work unit executes a portion of the for loop

A synchronization point is added
Prototype Implementation of BOLT Runtime

- Based on Intel’s open-source OpenMP runtime
  - http://openmp.llvm.org/
- Kept the original runtime API for the ABI compatibility
- Designed and implemented the threading layer using Argobots and modified the runtime internal layer
How to use BOLT?

Two ways to use BOLT
1. Compile your code with LLVM/Clang, Intel compiler, or GCC while linking BOLT
2. LD_PRELOAD=<bolt_installation_path>/lib/libomp.so (no reccompilation needed)
OpenUH OpenMP Validation Suite 3.1

<table>
<thead>
<tr>
<th></th>
<th>GCC 6.1</th>
<th>ICC 17.0.0 + Intel OpenMP</th>
<th>ICC 17.0.0 + BOLT (Argobots)</th>
<th>LLVM/clang 3.9 + BOLT (Argobots)</th>
</tr>
</thead>
<tbody>
<tr>
<td># of tested OpenMP constructs</td>
<td>62</td>
<td>62</td>
<td>62</td>
<td>62</td>
</tr>
<tr>
<td># of used tests</td>
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<td>123</td>
<td>123</td>
<td>123</td>
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<tr>
<td># of successful tests</td>
<td>118</td>
<td>118</td>
<td>122</td>
<td>112</td>
</tr>
<tr>
<td># of failed tests</td>
<td>5</td>
<td>5</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>Pass rate (%)</td>
<td>95.9</td>
<td>95.9</td>
<td>99.2</td>
<td>99.2</td>
</tr>
</tbody>
</table>

- The BOLT prototype functionally works well!
Nested Parallel Loop Microbenchmark

* The number of threads for the outer loop was fixed at 36.
Application Study: KIFMM

- Kernel-Independent Fast Multipole Method (KIFMM)
  - Offload dgemv operations to Intel MKL
- Evaluated the efficiency of the nested parallelism support in Intel OpenMP and BOLT during the Downward stage
  - 9 threads for the application (outer parallel region)

![Bar Chart]

- Lower is better
- oversubscription
Application Study: ACME mini-app

- ACME (Accelerated Climate Modeling for Energy)
  - Implementing additional levels of parallelism through OpenMP nested parallel loops for upcoming many-core machines
- Preliminary results of testing the transport_se mini-app version of HOMME (ACME’s CAM-SE dycore)

![Normalized Execution Time (%)]

<table>
<thead>
<tr>
<th>Normalized Execution Time (%)</th>
<th>H=16, V=1</th>
<th>H=8, V=2</th>
<th>H=4, V=4</th>
<th>H=4, V=8</th>
<th>H=8, V=4</th>
</tr>
</thead>
<tbody>
<tr>
<td>ICC + Intel OpenMP (15.0.0)</td>
<td>[Data]</td>
<td>[Data]</td>
<td>[Data]</td>
<td>[Data]</td>
<td>[Data]</td>
</tr>
<tr>
<td>ICC + BOLT (Argobots)</td>
<td>[Data]</td>
<td>[Data]</td>
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</tr>
</tbody>
</table>

Lower is better (up to 3.16x faster)

oversubscription
Summary

• BOLT: OpenMP over Lightweight Threads
  – More efficient support of nested parallelism with Argobots ULTs and tasklets
  – Preliminary results show that BOLT is promising
  – BOLT 1.0a1 pre-release is available at http://www.bolt-omp.org

• Argobots
  – A lightweight low-level threading/tasking framework
  – Provides efficient mechanisms, not policies, to users (library developers or compilers)
    • They can build their own solutions
BOLT Team

• **Maintainers**
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- Jonathan Lifflander (UIUC)
- Esteban Meneses (University of Pittsburgh)
- Huiwei Lu (ANL)
- Yanhua Sun (UIUC)
Try BOLT & Argobots

• BOLT
  – Pre-release 1.0a1 is available
  – [http://www.bolt-omp.org](http://www.bolt-omp.org)
  – git repository
    • [https://github.com/pmodels/bolt](https://github.com/pmodels/bolt)

• Argobots
  – Pre-release 1.0a1 is available
  – [http://www.argobots.org](http://www.argobots.org)
  – git repository
    • [https://github.com/pmodels/argobots](https://github.com/pmodels/argobots)
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Q&A

- Thank you for your attention!

Questions?